


# COMP424/524-06A

## Topics in Software Engineering

Part I – *Finite State Machines*

### 4. Supervisory Control

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### Modelling Reactive Systems

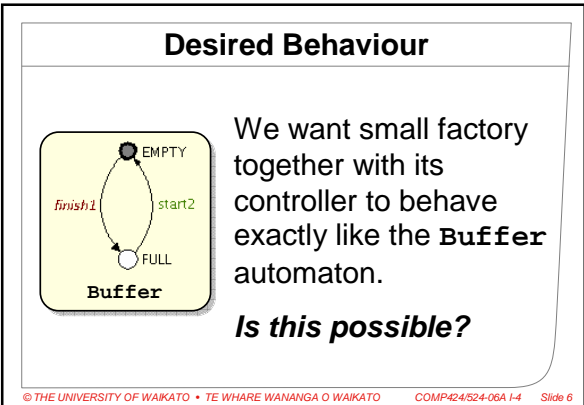
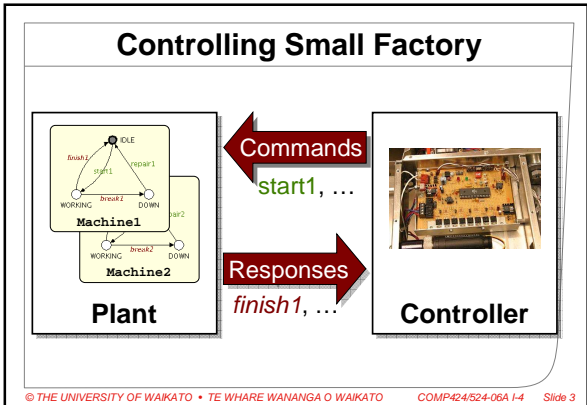
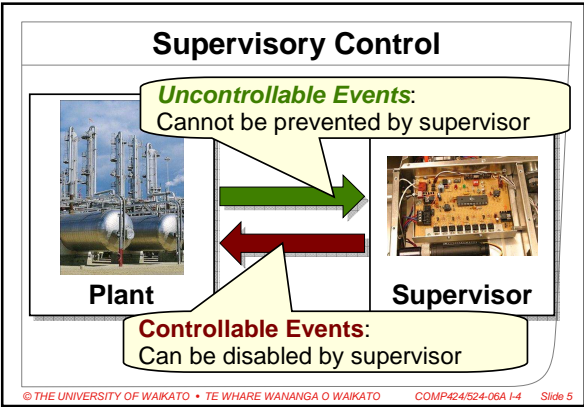
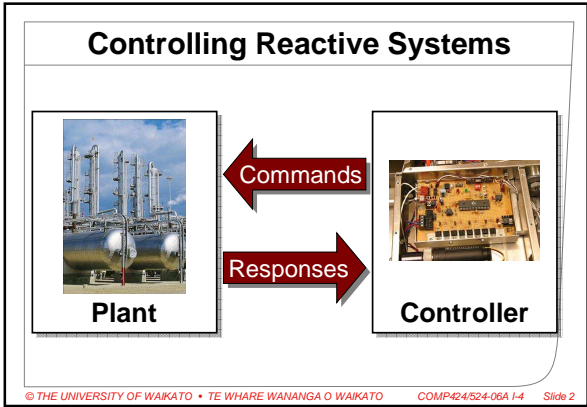
**Plant Model**

- Model of the system to be controlled
- Possible behaviour

**Specification**

- Model of the control program
- Desired behaviour

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### Controllability

Plant

Spec

**Definition**  
Let  $P$  and  $S$  be two automata.  
 $S$  is called **controllable** with respect to  $P$  if, for every state  $(q_p, q_s)$  reachable in  $P \parallel S$ , every uncontrollable event which is enabled in  $q_p$  also is enabled in  $q_s$ .

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### Small Factory is Not Controllable

<b>Machine1:</b> Working <b>Machine2:</b> Idle <b>Buffer:</b> Full	Plant can execute <b>finish1</b> Spec cannot execute <b>finish1</b>
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### Controllability Check Algorithm

To check whether plants  $P_1, \dots, P_n$  are controllable with respect to specifications  $S_1, \dots, S_m$ :

Add initial state  $q_0 = (q_{01}^P, \dots, q_{0n}^P, q_{01}^S, \dots, q_{0m}^S)$  to state set  $Q$   
**While** there are unvisited states  $q \in Q$  **do**  
   **For each** event  $e$  enabled by all plants  $P_i$  in state  $q$  **do**  
     **If**  $e$  is uncontrollable and there exists a specification  $S_j$  that cannot execute  $e$  in state  $q$  **then**  
       **return** "The system is not controllable."  
     **If**  $e$  can be executed by all specifications **then**  
       Compute successor state  $r$  such that  $q \xrightarrow{e} r$   
       Add  $r$  to state set  $Q$  if not yet present

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### Making Small Factory Controllable

**Observations**

- We cannot disable the uncontrollable event **finish1**.
- If the system ever enters state **WIF**, we have a problem.
- We can avoid entering this state by disabling the controllable event **start1** in state **IIF**.

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### Checking for Controllability

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### Reading

**Texts on Supervisory Control**

- C. G. Cassandras and S. Lafortune, *Introduction to discrete event systems*. Kluwer, 1999.
- W. M. Wonham, *Notes on control of discrete event systems*. Available on our course home page <http://www.cs.waikato.ac.nz/Teaching/COMP424A/>

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